

A Fully Abstract May Testing Semantics for Concurrent Objects

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Abstract

This paper provides a fully abstract semantics for a variant of the concurrent object calculus using the new may testing for concurrent object components and then characterises it using a trace semantics inspired by ML interaction algebra. The main result of this paper is to show that the trace semantics is fully abstract for may testing. This is the first such result for a concurrent object calculus.

Introduction

Abstraction-Carriers object calculus is a natural and useful investment features of object calculus such as encapsulate state, subtyping and session variables. Gordon and Hancock have concurrent features to the object calculus to produce the concurrent object calculus.

Our work on the object calculus has concentrated on the operational behaviour of object systems and type systems which provide type safety guarantees. The closest paper to ours is Gordon and Hancock's fully abstract semantics for the λ -calculus of the object calculus. There has been no work on providing a fully abstract semantics for concurrent λ -calculus objects.

In this paper we present the first fully abstract testing semantics for a variant of Gordon and Hancock's concurrent object calculus without subtyping. The lack of subtyping here allows a simpler presentation of the abstractions and traces but we anticipate that the proof techniques used here are robust enough to cater for subtyping as well. This semantics was inspired by ML interaction algebra which are a common tool for visualising interactions with object systems.

Interaction diagrams

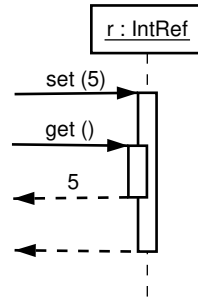
Interaction algebra is a particular sequence algebra were developed by Jacobson and are now part of the new Mobile Language standard. Interaction algebra records the messages sent between objects of a component in an object system. These messages include the

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an returns interaction a ra s an c u e ot her or s o e s s a e but we w not use t ese n t s paper t

A s p e interaction w t an nte er re e r e n c e o b e c t r o e t y p e I n t R e f

sequence diagrams can be used for illustrating applications or examples



Here two threads independently call methods of the object `r` creating a race condition. In our textual representation we have the threads names and we decorate each message with the thread responsible for the message.

```
thread1 callr.set( 5)
thread2 callr.get
```

- Messages are not in or out of a process or attached in or out of a return
- Messages are decorated with their identifiers
- Messages may include references

We have only used a very small subset of sequence calculus which in turn is a very small subset of ML but in this paper we will show that this small subset is very expressive and in particular provides a fully abstract semantics.

The object calculus

The object calculus is a natural language for describing object based programming. Abelson and Cardon provide a type system and operational semantics for a variety of object calculus and prove type safety for the π calculus. Gordon and Haridi have since extended this language to include concurrent features.

In this paper we shall investigate a variant of Gordon and Haridi's concurrent object calculus which includes

- A heap of named objects and threads
- Threads can call or update object methods can compare object or thread names, or equality can create new objects and threads and can discover their own thread name
- An operational semantics based on the π calculus and a simple type system
- A trace semantics as discussed in section 1.1

We are not considering any of the more advanced features of the object calculus or the concurrent object calculus such as recursive types, object cloning, object cloning, this is sufficient for simplicity and we do not see any technical problems with incorporating these features into our language.

In another strand of research, DeBasio and Fisher have also investigated a calculus for object based concurrent object based systems. As with Abelson and Cardon's object calculus and its various extensions, the expressiveness of DeBasio and Fisher's works as a lambda type system and safety properties for the π calculus.

Full abstraction

The problem of full abstraction was first introduced by Milner and investigated in depth by Plotkin. Full abstraction was first proposed for variants of the λ calculus but has since been investigated for process algebras, the π calculus, the ν calculus, Concurrent ML and the λ calculus object calculus.

we can then define the *may testing preorder* as $C \sqsubseteq_{\text{ay}} C'$ whenever

for any appropriate type C
 $C \sqsubseteq_{\text{ay}} C'$ is successful then $C \sqsubseteq_{\text{ay}} C'$ is successful

Unfortunately a thorough analysis is very simple to define and is quite intuitive. May testing is often very difficult to reason about directly because of the quantification over any appropriate type C . In practice we require a proof technique which we can use to show results about may testing.

One approach is to use a *trace semantics* given by the finite possible executions of components $C \stackrel{s}{=} C'$ where s is a sequence of events. We then write $\text{Traces}(C)$ for the set of all traces of C . We say that

- traces are *sound* for may testing when $\text{Traces}(C) \subseteq \text{Traces}(C')$ implies $C \sqsubseteq_{\text{ay}} C'$
- traces are *complete* for may testing when $C \sqsubseteq_{\text{ay}} C'$ implies $\text{Traces}(C) \subseteq \text{Traces}(C')$
- traces are *fully abstract* when $T_{j11.993tTJ/R1.991Tf1.19Tdfor-2may-22.9test-21.9ing-2.whenTJsi.9911.so/R11.9}$

| | |
|------------|---|
| Components | $C = \{C \mid \forall n \in \mathbb{N}. C \mid n \in \mathbb{N}\}$ |
| Objects | $O = \{l = M, \dots, l = M\}$ |
| Methods | $M = \{n \in \mathbb{N}. \lambda(x \in T, \dots, x \in T). t\}$ |
| Areas | $t = v \mid \text{stop} \mid \text{let } x \in T = e \text{ in } t$ |

definition of expressions

- A **value** $f = v$ in an object λ syntax syntax_f or a **value** $f = \zeta(n, T, \lambda(\cdot, v))$
- A **type** $f = T$ in an object λ syntax syntax_f or a **type** $f = (T)$
- A **access expression** $v.f$ λ syntax syntax_f or a **access** $v.f()$
- A **update expression** $n.f = v$ λ syntax syntax_f or a **update** $n.f = (\zeta(p, T, \lambda(\cdot, v)))$

In addition we have restricted any subexpressions of an expression to be values rather than expressions or expressions or expressions. In a **value** $v.l(\vec{v})$ we require the object and the arguments to be values rather than expressions. This is a less restrictive operation since it is easier to be a value than an expression. The expression $e.l(\vec{e})$ does not restrict the expression of the arguments or expressions. For example we can write $(e.l(\vec{e}))$ (let $x = e$ in let $\vec{x} = \vec{e}$ in $x.l(\vec{x})$) or any other expression as the

A thread t consists of a stack of expressions terminated either by a return value

$$\text{let } x = T = e \text{ in } \dots \text{let } x_n = T_n = e_n \text{ in } v$$

or by a special `stop` thread

$$\text{let } x = T = e \text{ in } \dots \text{let } x_n = T_n = e_n \text{ in stop}$$

Each expression is either a thread or

- an expression `if $v = v$ then e else e`
- a method call `$v.l(\vec{v})$`
- a method lookup `$n.l \ M$` on a name object
- a new object `new O`
- a new thread `new t` or
- the current thread name `currentthread`

Each value is a primitive or a variable and we defer the discussion of types until section 11.

• Static semantics

The static semantics of our concurrent object calculus is given in Figures 11. Most of the rules are straightforward adaptations of those given by Abadi and Cardelli. The main difference is $\Delta \vdash C \vdash \Theta$ which is read as the component C uses names Δ and the names Θ . For example, we define $C(v \vdash C)$ as `IntRef` as

$$\begin{aligned} C(v \vdash p) \\ \text{contents} = v, \\ \text{set} = \zeta(\text{this IntRef} . \lambda(x \text{ Int} . \text{this.contents} = x, x), \\ \text{get} = \zeta(\text{this IntRef} . \lambda() . \text{this.contents} \end{aligned}$$

$$\begin{aligned} C \vdash n \\ \text{let } x = p.\text{get}() \text{ in } p.\text{set}(x, \text{stop}) \end{aligned}$$

$$\begin{aligned} \text{IntRef} \\ \text{contents} \text{ Int} \end{aligned}$$

$$\frac{\Delta \vdash \tau}{\Delta \vdash \tau} \quad \frac{\Delta, n \vdash T \quad \Delta \vdash O \quad T}{\Delta \vdash n \cdot O \quad (n \vdash T)} \quad \frac{\Delta, n \text{ thread } \vdash t \quad \text{none}}{\Delta \vdash n \cdot t \quad (n \text{ thread})}$$

$$\frac{\Delta, \Theta \vdash C \quad \Theta \quad \Delta, \Theta \vdash C \quad \Theta}{\Delta \vdash (C \quad C \quad (\Theta, \Theta))} \quad \frac{\Delta \vdash C \quad \Theta, n \vdash T}{\Delta \vdash \nu(n \vdash T \quad C \quad \Theta)}$$

For ure — u es_i or u e ent $\Delta \vdash C \quad \Theta$

$$\frac{\Gamma, \Delta \vdash M \quad T.l \quad \dots \quad \Gamma, \Delta \vdash M_k \quad T.l_k}{\Gamma, \Delta \vdash l = M, \dots, l_k = M_k \quad T}$$

For ure — u es_i or u e ent $\Gamma, \Delta \vdash O \quad T$ when $T = l \quad L, \dots, l_k \quad L_k$

$$\frac{\Gamma, x \vdash T, \dots, x_k \vdash T_k, \Delta, n \vdash T \quad t \quad U}{\Gamma, \Delta \vdash \zeta(n \vdash T \quad \lambda(x \vdash T, \dots, x_k \vdash T_k \quad t \quad T.l)}$$

For ure — u es_i or u e ent $\Gamma, \Delta \vdash M \quad T.l$ when $T = \dots, l \quad (T, \dots, T_k \quad U, \dots \text{ an } T.l \text{ s t e}$
recor l se ecte_i ro T

$$\frac{\Gamma, \Delta \vdash v \quad T \quad \Gamma, \Delta \vdash v \quad T \quad \Gamma, \Delta \vdash e \quad T \quad \Gamma, \Delta \vdash e \quad T}{\Gamma, \Delta \vdash \text{if } v = v \text{ then } e \text{ else } e \quad T}$$

$$\frac{\Gamma, \Delta \vdash v \quad \dots, l \quad (T, \dots, T_k \quad T, \dots \quad \Gamma, \Delta \vdash v \quad T \quad \dots \quad \Gamma, \Delta \vdash v_k \quad T_k}{\Gamma, \Delta \vdash \nu.l(v, \dots, v_k \quad T)} \quad \frac{\Gamma, \Delta \vdash n \vdash T \quad \Gamma, \Delta \vdash M \quad T.l}{\Gamma, \Delta \vdash n.l \quad M \quad T}$$

$$\frac{\Gamma, \Delta \vdash O \quad T}{\Gamma, \Delta \vdash \text{new } O \quad T} \quad \frac{\Gamma, \Delta \vdash t \quad T}{\Gamma, \Delta \vdash \text{new } t \quad \text{thread}} \quad \frac{}{\Gamma, \Delta \vdash \text{currentthread} \quad \text{thread}}$$

$$\frac{\Gamma, \Delta \vdash e \quad T \quad \Gamma, x \vdash T, \Delta \vdash t \quad T}{\Gamma, \Delta \vdash \text{let } x \vdash T = e \text{ in } t \quad T} \quad \frac{}{\Gamma, \Delta \vdash \text{stop} \quad T} \quad \frac{}{\Gamma, x \vdash T, \Gamma, \Delta \vdash x \quad T} \quad \frac{}{\Gamma, \Delta, n \vdash T, \Delta \vdash n \quad T}$$

For ure — u es_i or u e ent $\Gamma, \Delta \vdash e \quad T$

var.ab e contexts $\Gamma = x \vdash T, \dots, x \vdash T$ a e contexts $\Delta, \Theta, \Sigma, \Phi = n \vdash T, \dots, n \vdash T$

In var.ab e contexts var.ab es ust be un.que an are v.eve up to reor er.n !
In na e contexts na es ust be un.que types ust not be none an are v.eve up to reor er.n !

For ure — yntax o_i na e an var.ab e contexts

Whenever $\Delta \vdash C \in \Theta$ contains a subexpression of the form n or n appears in Θ

As a sentence to capture the notion of software engineering requirements you do not export mutable cells instead they should export mutable get and set methods. The configurations C and C' above are write close since they update a mutable component which writes directly to p .contents is not write close

$C \rightarrow_n C'$ let $x = p$.contents in p .contents = x ; stop

For the remainder of the paper we will require components to be write close open a fully abstract semantics such as per since we do not need to directly

3 Dynamic semantics

The dynamic semantics for our concurrent object calculus is given in Figures 1 and 2. The three relations between components

- structural congruence represents the least congruence on components which satisfies the axioms in Figure 1
- $C \rightarrow C'$ when C can reduce to C' by the interaction of a thread and an object either a call or a return update
- $C \rightarrow^\beta C'$ when C can reduce to C' by a thread action in dependent L. The name

t

$$C \quad \nu(n \ T \ .C) \quad \nu(n \ T \ .(C \ C) \quad \nu(n \ T \ .\nu(n \ T \ .C) \quad \nu(n \ T \ .\nu(n \ T \ .C)$$

Fix are Axioms for structural congruence where n is not free in C

| | | | |
|---|---------|---|---|
| $n \ let \ x \ T = v \ in \ t$ | β | $n \ t \ v/x$ | |
| $n \ let \ x \ T = (let \ x \ T = e \ in \ e) \ in \ t$ | β | $n \ let \ x \ T = e \ in \ (let \ x \ T = e \ in \ t)$ | |
| $n \ let \ x \ T = (if \ v = v \ then \ e \ else \ e) \ in \ t$ | β | $n \ let \ x \ T = e \ in \ t$ | |
| $n \ let \ x \ T = (if \ v = v \ then \ e \ else \ e) \ in \ t$ | β | $n \ let \ x \ T = e \ in \ t$ | |
| $n \ let \ x \ T = new \ O \ in \ t$ | β | $\nu(p \ T \ .(p \ O \ n \ let \ x \ T = p \ in \ t)$ | $v = v$ $else$ |

. **Testing preorder**

we now need the test semantics for our concurrent object calculus. We do this by defining a notion of *barb*

~~(Δ, n thread - C~~

the base and the other would have been reached by the component and test actually interacting. This operation of merging is done below.

• The merge operator

Define the partial merge operator $C \bowtie C$ on components as the symmetric operator defined up to where

$$\begin{aligned} (v) C \bowtie C &= C \\ (\nu(p, T). C) \bowtie C &= \nu(p, T).(C \bowtie C) \\ (p O C) \bowtie C &= p O (C \bowtie C) \\ (p t C) \bowtie C &= p t (C \bowtie C) \\ (n t C) \bowtie (n t C) &= n t \bowtie t (C \bowtie C) \end{aligned}$$

when $n \in \text{dom}(C, C)$ and $p \in \text{fn}(C)$. The notation and the partial merge operator $t \bowtie t$ on traces is as the symmetric operator where

$$\begin{aligned} (\text{let } x.T = \text{block in } t \bowtie \text{stop} &= \text{stop} \\ (\text{let } x.T = \text{block in } t \bowtie (\text{let } y.U = \text{return}(y.T) \text{ in } t) &= (\text{let } y.U = \text{block in } t \bowtie (t \nu/x \\ (\text{let } x.T = \text{block in } t \bowtie (\text{let } y.U = e \text{ in } t) &= \text{let } y.U = e \text{ in } ((\text{let } x.T = \text{block in } t \bowtie t \end{aligned}$$

when e is basic, return-free and $y \in \text{fv}(t)$.

Lemma . If $\Delta \vdash (C \subseteq \Theta)$ then $(C \bowtie C) \subseteq (C \subseteq \Theta)$.

Proof An induction on the definition of $C \bowtie C$. □

Lemma . If $C \bowtie C \subseteq C$ and $C \subseteq b$ then $C \subseteq b$.

Proof An induction on the definition of $C \bowtie C$. □

• Trace composition and decomposition

Given a trace s we write s_i for the elementary trace

$$\varepsilon = \varepsilon C \quad \text{An} \quad \forall \text{BI IMtrue} \quad \text{H, B, C, ID, E, Ie been}$$

Proof Given in Appendix A □

Corollary . For any components $(\Delta, \Phi \dashv C \dashv \Theta, \Sigma)$ and $(\Theta, \Phi \dashv C \dashv \Delta, \Sigma)$ such that $C \approx C' \dashv C''$ and $C' \dashv b$ then there exists some trace s such that $(\Delta, \Phi \dashv C \dashv \Theta, \Sigma) \xrightarrow{s} (\Delta, \Phi \dashv C' \dashv \Theta, \Sigma)$ and $(\Theta, \Phi \dashv C \dashv \Delta, \Sigma) \xrightarrow{s} (\Theta, \Phi \dashv C'' \dashv \Delta, \Sigma)$ where either $C' \dashv b$ or $C'' \dashv b$.

Proof We now trace at $C' \dashv b$ with respect to s using trace at $C \dashv C'$ or so we can successively trace at $C' \dashv b$ we use proposition 1 part 1 to obtain a trace s' such that

$$\begin{aligned} (\Delta, \Phi \dashv C \dashv \Theta, \Sigma) &\xrightarrow{s} (\Delta, \Phi \dashv C' \dashv \Theta, \Sigma) \\ (\Theta, \Phi \dashv C \dashv \Delta, \Sigma) &\xrightarrow{s} (\Theta, \Phi \dashv C'' \dashv \Delta, \Sigma) \end{aligned}$$

where $v(\Delta, \Theta, \Sigma) \setminus v(\Delta, \Theta, \Sigma) \cdot (C \approx C' \dashv C'')$. Given trace at $C' \dashv b$ we now trace at $(C \approx C' \dashv b)$ as well. By the definition of \approx we see that one of the following or their symmetric counterparts must hold

- $C' \dashv b$ and we are done
- $C \dashv v(\Delta) \cdot (n \ t \ C' \dashv b)$ and $C \dashv v(\Delta) \cdot (n \ t \ C'' \dashv b)$ where $n \ t \ \approx \ t \dashv b'$ we now proceed by an induction on the definition of $t \ \approx \ t'$ to show that for a successively C' and C'' we can find s' where

$$\begin{aligned} (\Delta, \Phi \dashv C \dashv \Theta, \Sigma) &\xrightarrow{s} (\Delta, \Phi \dashv C' \dashv \Theta, \Sigma) \\ (\Theta, \Phi \dashv C \dashv \Delta, \Sigma) &\xrightarrow{s} (\Theta, \Phi \dashv C'' \dashv \Delta, \Sigma) \end{aligned}$$

and either $C' \dashv b$ or $C'' \dashv b$ there are two cases up to symmetry

- If $t = \text{let } x \ T = \text{block in } t$ and $t' = \text{let } y \ U = b.\text{succ}(\text{ in } t \ t')$ then $C' \dashv b$
- If $t = \text{let } x \ T = \text{block in } t$ and $t' = \text{let } y \ U = \text{return}(v \ T \ \text{in } t \ t')$ then we have

$$\begin{aligned} (\Delta, \Phi \dashv C \dashv \Theta, \Sigma) &\xrightarrow{v(\Delta) \cdot (n \ \text{return } v \ ?)} (\Delta, \Delta, \Phi \dashv v(\Delta) \cdot (n \ t \ v/x \dashv \Theta, \Sigma) \\ (\Theta, \Phi \dashv C \dashv \Delta, \Sigma) &\xrightarrow{v(\Delta) \cdot (n \ \text{return } v)} (\Theta, \Phi \dashv v(\Delta) \cdot (n \ \text{let } y \ U = \text{block in } t \dashv \Delta, \Delta, \Sigma) \end{aligned}$$

where $\Delta = (\Delta, \Delta)$ and moreover

$$n \ t \ \approx \ t \quad n \ (\text{let } y \ U = \text{block in } t \ \approx \ t \ v/x \dashv b)$$

so by an inductive hypothesis

$$\begin{aligned} (\Delta, \Phi \dashv C \dashv \Theta, \Sigma) &\xrightarrow{v(\Delta) \cdot (n \ \text{return } v \ ?)} \xrightarrow{s} (\Delta, \Phi \dashv C' \dashv \Theta, \Sigma) \\ (\Theta, \Phi \dashv C \dashv \Delta, \Sigma) &\xrightarrow{v(\Delta) \cdot (n \ \text{return } v)} \xrightarrow{s} (\Theta, \Phi \dashv C'' \dashv \Delta, \Sigma) \end{aligned}$$

and either $C' \dashv b$ or $C'' \dashv b$ as required □

§ Proof of soundness

Theorem 1. (Soundness of traces for may testing) *If* $\text{Traces}(\Delta \dashv\!\!\!-\! \mathcal{C} \dashv\!\!\!-\! \Theta) = \text{Traces}(\Delta \dashv\!\!\!-\! \mathcal{C} \dashv\!\!\!-\! \Theta)$ *then* $\Delta \models \mathcal{C} \sqsubseteq_{\text{may}} \mathcal{C} \dashv\!\!\!-\! \Theta$

Proof suppose t at $\text{Traces}(\Delta \dashv\!\!\!-\! \mathcal{C} \dashv\!\!\!-\! \Theta) \neq \text{Traces}(\Delta \dashv\!\!\!-\! \mathcal{C} \dashv\!\!\!-\! \Theta)$ and t at we have $(\Theta, b \text{ barb } \mathcal{C} \dashv\!\!\!-\! \Delta)$ such t at $(\mathcal{C} \dashv\!\!\!-\! \mathcal{C} \dashv\!\!\!-\! b)$, we must show t at $(\mathcal{C} \dashv\!\!\!-\! \mathcal{C} \dashv\!\!\!-\! b)$ as well. Now since $(\mathcal{C} \dashv\!\!\!-\! \mathcal{C} \dashv\!\!\!-\! b)$ we can use Corollary 1 to get

$$\begin{aligned} (\Delta, b \text{ barb } \mathcal{C} \dashv\!\!\!-\! \Theta) &\stackrel{s}{=} (\Delta, b \text{ barb } \mathcal{C} \dashv\!\!\!-\! \Theta, \Sigma) \\ (\Theta, b \text{ barb } \mathcal{C} \dashv\!\!\!-\! \Delta) &\stackrel{s}{=} (\Theta, b \text{ barb } \mathcal{C} \dashv\!\!\!-\! \Delta, \Sigma) \end{aligned}$$

$\Delta - \epsilon$ trace Θ

n

- $\mathbb{I}_{\vec{r}} n \text{ threads } (s \text{ t}^{\dagger} \text{en } n \text{ s ba ance } \Delta n s$
- $\mathbb{I}_{\vec{r}} n \text{ s ba ance } \Delta n s \text{ an } s \text{ t}^{\dagger} \text{en } n \text{ s ba ance } \Delta n s s \uparrow$
- $\mathbb{I}_{\vec{r}} n \text{ s ba ance } \Delta n s \text{ t}^{\dagger} \text{en } n \text{ s ba ance } \Delta n v(\Delta . n \text{ call } p.l(\vec{n} \text{ ? } s v(\Theta . n \text{ return } v \text{ ?}$
- $\mathbb{I}_{\vec{r}} n \text{ s ba ance } \Delta n s \text{ t}^{\dagger} \text{en } n \text{ s ba ance } \Delta n v(\Theta . n \text{ call } p.l(\vec{n} \text{ ? } s v(\Delta . n \text{ return } v \text{ ?}$

De ne $\text{popn}(s) =$

- $\mathbb{I}_{\vec{r}} n \text{ s ba ance } \Delta n s \text{ t}^{\dagger} \text{en } \text{popn}(s) = \uparrow$
- $\mathbb{I}_{\vec{r}} n \text{ s ba ance } \Delta n s \text{ an } a =$

Proof Easy induction on s

□

Lemma 3.1

1. If C is block/return free and $(\Delta - C - \Theta \stackrel{s}{=} \frac{v(\Theta . n \text{ return } v)}{\text{---}})$ then $s = s \ v(\Delta . n \text{ call } p.l(\vec{v}) \ ? s)$ where n is balanced in s .
2. If C is block/return free and $(\Delta - C - \Theta \stackrel{s}{=} \frac{v(\Delta . n \text{ return } v \ ?)}{\text{---}})$ then $s = s \ v(\Theta . n \text{ call } p.l(\vec{v}) \ s)$ where n is balanced in s .

Proof We prove these properties simultaneously by an induction on the length of s . We only show the return case, for the call case can be shown in a similar manner. By analysis of the rules of the ts we have

$$(\Delta - C - \Theta \stackrel{s}{=} (\Delta - C - n \text{ let } x = T = \text{return}(v \ U \ \text{in } t - \Theta \ \frac{v(\Theta . n \text{ return } v)}{\text{---}}))$$

now partition s into $s \ s \ p.c \ \text{in } s$

$$\Delta \xrightarrow{s} \text{trace } \Theta$$

and we notice that because C is a $\text{return } v$ we can apply Lemma 1 to get

$$s = s \cdot v(\Delta \cdot n \text{ call } p.l(\vec{v} \ ? \ s$$

where n is a $\text{call } p.l(\vec{v} \ ? \ s$. Given that we see that

$$\text{popn}(s \cdot v(\Delta \cdot n \text{ call } p.l(\vec{v} \ ? \ s) = v(\Delta \cdot n \text{ call } p.l(\vec{v} \ ? \ s$$

hence

$$\text{popn}(s) = v(\Delta \cdot n \text{ call } p.l(\vec{v} \ ? \ s$$

And the side conditions on the transition rule $\text{call } p.l(\vec{v} \ ? \ s$ guarantee that

$$\text{dom}(\Theta) \cap \text{fn}(v)$$

is empty. Now by induction we act that prefixes of type traces are also type that

$$\Delta \xrightarrow{s} v(\Delta \cdot n \text{ call } p.l(\vec{v} \ ? \ s) \text{ trace } \Theta$$

and we see that that must have been an error in a hypothesis

$$s, \Theta, \Theta(s) \xrightarrow{p} \dots (\vec{U} \ U \dots$$

which by weakening gives us

$$s, \Theta, \Theta(s) \xrightarrow{p} \dots (\vec{U} \ U \dots$$

Lastly because

$$(\Delta, \Delta(s) \xrightarrow{C} \Theta, \Theta(s)$$

and

$$C \xrightarrow{n} \text{let } x = T \text{ return } v \text{ in } t$$

we see that

$$s, \Delta, \Delta(s), \Theta, \Theta(s), \Theta \xrightarrow{v} U$$

so by Lemma 1 to either we have the type side conditions or call input transitions we have that $U = U$ and so

$$s, \Delta, \Delta(s), \Theta, \Theta(s), \Theta \xrightarrow{v} U$$

we connect the state elements to either to see that they or the hypotheses of the type rule which allows us to conclude

$$\Delta \xrightarrow{s} v(\Theta \cdot n \text{ return } v) \text{ trace } \Theta$$

as required

Case $s = s \cdot v(\Delta \cdot n \text{ return } v)$ refer to previous case

□

Information order on traces

The information preorder on traces $\Delta \rightarrow_S \text{trace } \Theta$ is generated by axioms where in each case we require both sides of the equation to be well type traces

$$\begin{aligned} & \Delta \rightarrow_S \rightarrow_S \text{trace } \Theta \\ & \Delta \rightarrow_S \gamma \rightarrow_S \text{trace } \Theta \\ & \Delta \rightarrow_S \gamma \gamma \rightarrow_S \text{trace } \Theta \\ & \Delta \rightarrow_S \text{sv}(\Delta \rightarrow_S \gamma \gamma \rightarrow_S \text{trace } \Theta) \rightarrow_S \text{sv}(\Delta \rightarrow_S \gamma \rightarrow_S \text{trace } \Theta) \\ & \Delta \rightarrow_S \text{sv}(\Theta \rightarrow_S \gamma \rightarrow_S \text{trace } \Theta) \rightarrow_S \text{sv}(\Theta \rightarrow_S \gamma \rightarrow_S \text{trace } \Theta) \end{aligned}$$

Lemma . (Information Order Duality) *If $\Delta \rightarrow_S \gamma \rightarrow_S \text{trace } \Theta$ and $\text{fn}(\gamma \rightarrow_S \Theta) = \emptyset$ and $\gamma \rightarrow_S r$ then $\Theta \rightarrow_S r \rightarrow_S \text{trace } \Delta$.*

Proof We write $\Delta \rightarrow_S \rightarrow_S \text{trace } \Theta$ as $\Delta \rightarrow_S \rightarrow_S \text{trace } \Theta$ can be derived using n instances of

Proposition . (Information Order Closure) *If $(\Delta \rightarrow_C \Theta \stackrel{s}{=} \text{ and } \Delta \text{ } r \text{ } s \text{ } \text{trace } \Theta$*
then $(\Delta \rightarrow_C \Theta \stackrel{r}{=} \text{ .$

Proof . Now that the following lemmas can be completed when $\text{thread}(\gamma) = \text{thread}(\gamma \text{---}$

$\text{Comp}(\Delta \xrightarrow{s} \text{trace } \Theta = v(\Theta(s), \text{ref} \text{ Ref}, \text{state}_\varepsilon \text{ State} \cdot ($
 $\text{ref val} = \text{state}_\varepsilon$
 $\text{state}_\varepsilon \text{ State}(\Delta \xrightarrow{\varepsilon} \text{trace } \Theta$
 $\prod\{p \ l_i = \text{ref.val.inCall}_{p,l_i} L_i \mid i = \dots n \} \cup \prod\{p \ l_i = L_i \mid i = \dots n \} \quad \Theta, \Theta(s) \}$
 $\prod\{n \ \text{ref.val.out}_{\text{none}}(\text{thread } \Theta, \Theta(s) \}$

$\text{Ref} = \text{val} \text{ State}$

$\text{State} = \text{out}_T(\text{ } T, \text{inReturn}_T(\text{ } T \text{ } T, \text{inCall}_{p,l} L$

$\text{State}(\Delta \xrightarrow{r} \text{trace } \Theta = ($
 $\text{out}_T = \text{Out}_T(\Delta \xrightarrow{r} \text{trace } \Theta ,$
 $\text{inReturn}_T = \text{InReturn}_T(\Delta \xrightarrow{r} \text{trace } \Theta ,$
 $\text{inCall}_{p,l} = \text{InCall}_{p,l}(\Delta \xrightarrow{r} \text{trace } \Theta$

$\text{Out}_T(\Delta \xrightarrow{r} \text{trace } \Theta = \lambda(\cdot ($
 $\text{when } ra \text{ } s \text{ an } a = v(\Theta \cdot n \ \text{call } p.l(\vec{v} \text{ an } \Delta, \Theta, \Delta(r), \Theta(r), \Theta \ p.l(\vec{v} \text{ } U$
 $\text{if currentthread} = n \text{ then}$
 $\text{ref.val} = \text{new State}(\Delta \xrightarrow{ra} \text{trace } \Theta ,$
 $\text{ref.val.inReturn}_U(p.l(\vec{v} ,$
 $\text{ref.val.out}_T($
 $\text{when } ra \text{ } s \text{ an } a = v(\Theta \cdot n \ \text{return } v \text{ an } \Delta, \Theta, \Delta(r), \Theta(r), \Theta \text{ } \text{ } T$
 $\text{if currentthread} = n \text{ then}$
 $\text{ref.val} = \text{new State}(\Delta \xrightarrow{ra} \text{trace } \Theta ,$
 $\text{ } v$
 otherwise
 stop

$\text{InReturn}_T(\Delta \xrightarrow{r} \text{trace } \Theta = \lambda(x \ T \cdot ($
 $\text{when } ra \text{ } s \text{ an } a = v(\Delta \cdot n \ \text{return } v \text{ } \text{ an } \Delta, \Theta, \Delta(r), \Theta(r), \Delta \text{ } \text{ } T$
 $\text{if } \Delta, \Theta, \Delta(r), \Theta(r) \text{ (currentthread, } x = v(\Delta \cdot (n, v \text{ then}$
 $\text{ref.val} = \text{new State}(\Delta \xrightarrow{ra} \text{trace } \Theta ,$
 $\text{ } v$
 otherwise
 stop

$\text{InCall}_{p,l}(\vec{T} \ T(\Delta \xrightarrow{r} \text{trace } \Theta = \lambda(\vec{x} \ \vec{T} \cdot ($
 $\text{when } ra \text{ } s \text{ an } a = v(\Delta \cdot n \ \text{call } p.l(\vec{v} \text{ } \text{ an } \Delta, \Theta, \Delta(r), \Theta(r), \Delta \text{ } \text{ } \vec{T}$
 $\text{if } \Delta, \Theta, \Delta(r), \Theta(r) \text{ (currentthread, } \vec{x} = v(\Delta \cdot (n, \vec{v} \text{ then}$
 $\text{ref.val} = \text{new State}(\Delta \xrightarrow{ra} \text{trace } \Theta ,$
 $\text{ref.val.out}_T($
 otherwise
 stop

Figure 1. Definition of $\text{Comp}(\Delta \xrightarrow{s} \text{trace } \Theta$

if $\Delta (v, \vec{v} = v(p, U, \vec{n}, \vec{T}) \cdot (p, \vec{p})$ then $t = t$
 if $\Delta (v, \vec{v} = v(p, U, \vec{n}, \vec{T}) \cdot (p, \vec{p})$ then $t =$ if $v \Delta^- (U$ then
 (if $\Delta_{\vec{p}} U (\vec{v} = v(\vec{n}, \vec{T}) \cdot (\vec{p})$ then $t = v/p$ else stop
 if $\Delta (v, \vec{v}$

• **Proof of completeness**

Theorem 1.1 (Completeness of traces for may testing) *If $\Delta \models C \sqsubseteq_{may} C' \ominus$ then $\text{Traces}(\Delta \vdash C \ominus) = \text{Traces}(\Delta \vdash C' \ominus)$.*

Proof Choose any trace $s \in \text{Traces}(\Delta \vdash C' \ominus)$. (= ((((

1. If $C \cong C \oplus D \oplus E$ then there exist components such that $C \cong D \oplus E$ and $C \cong D \oplus E$ with $D \oplus D \cong D$ and $E \oplus E \cong E$.

2. If $C \cong C \oplus \nu(\vec{n}, \vec{T}) \cdot C$ then there exist components such that $C \cong \nu(\vec{n}, \vec{T}) \cdot C$ and $C \cong \nu(\vec{n}, \vec{T}) \cdot C$ with $(\vec{n}, \vec{T}) = (\vec{n}, \vec{T}) \oplus (\vec{n}, \vec{T})$ and $C \cong C \oplus C$.

Proof proved by induction on the evaluation of $C \cong C$. □

Lemma A. If $C \cong C \oplus C$ and $C \cong C^{\beta} \oplus C^{\beta}$

- **Case** $(\gamma = \nu(\vec{n} \vec{T} . n \text{ call } p.l(\vec{v} \text{ an } n \Sigma))$
 as to the previous case

- **Case** $(\gamma = \nu(\vec{n} \vec{T} . n \text{ return } v))$

since $(\Delta, \Phi \vdash_C \Theta, \Sigma \stackrel{\gamma}{\sim} (\Delta, \Phi \vdash_C \Theta, \Sigma)$ we must have that

$$\begin{aligned} C & \nu(\vec{p} \vec{U} . (C \text{ n let } x \ T = \text{block in } t) \\ C & \nu(\vec{p} \vec{U} . (C \text{ n } t \ v/x) \\ \Delta & = \Delta, \vec{n} \vec{T} \\ \Theta & = \Theta \\ \Sigma & = \Sigma \end{aligned}$$

since $(\Theta, \Phi \vdash_C \Delta, \Sigma \stackrel{\gamma}{\sim} (\Theta, \Phi \vdash_C \Delta, \Sigma)$ we must have that

$$\begin{aligned} C & \nu(\vec{n} \vec{T} . \nu(\vec{p} \vec{U} . (C \text{ n let } y \ U = \text{return}(v \ T \text{ in } t) \\ C & \nu(\vec{p} \vec{U} . (C \text{ n let } y \ U = \text{block in } t) \end{aligned}$$

we then show that

$$C \ \& \ C \ \nu(\vec{n} \vec{T} . \nu(\vec{p} \vec{U} . \nu(\vec{p} \vec{U} . ((C \ \& \ C \text{ n let } y \ U = \text{block in } t) \ \& \ (t \ v/x) \text{ an } t) \text{ at}$$

$$C \ \& \ C \ \nu(\vec{p} \vec{U} . \nu(\vec{p} \vec{U} . ((C \ \& \ C \text{ n let } y \ U = \text{block in } t) \ \& \ (t \ v/x) \text{ an } t) \text{ at}$$

and so

$$\nu(\Delta, \Theta, \Sigma \setminus \Delta, \Theta, \Sigma) . (C \ \& \ C \ \ C)$$

as required □

Composition follows by induction on the derivation of $(\Delta, \Phi \vdash_C \Theta, \Sigma \stackrel{s}{\sim} (\Delta, \Phi \vdash_C \Theta, \Sigma)$ and $(\Theta, \Phi \vdash_C \Delta, \Sigma \stackrel{s}{\sim} (\Theta, \Phi \vdash_C \Delta, \Sigma)$ a use of Lemma A.1 and A.2

A. Decomposition

we show the result as follows by decomposition

Lemma A. For any $\Delta, \Phi \vdash_C \Theta, \Sigma$ and $\Theta, \Phi \vdash_C \Delta, \Sigma$ if $(C \ \& \ C \ \nu(\vec{n} \vec{T} . (C \text{ n let } x \ T = e \text{ in } t))$ then either we have:

$$\begin{aligned} (\Delta, \Phi \vdash_C \Theta, \Sigma \stackrel{s}{\sim} (\Delta, \Phi \ \nu(\vec{n} \vec{T} . (C \text{ n let } x \ T = e \text{ in } t) \ \Theta, \Sigma) \\ (\Theta, \Phi \vdash_C \Delta, \Sigma \stackrel{s}{\sim} (\Theta, \Phi \vdash_C \Delta, \Sigma) \end{aligned}$$

where:

$$\nu(\Delta, \Theta, \Sigma \setminus \Delta, \Theta, \Sigma) . \nu(\vec{n} \vec{T} . (C \text{ n } t) \ \& \ C \ \nu(\vec{n} \vec{T} . (C \text{ n } t)$$

or symmetrically, swapping the roles of C and C .

Proof An induction on the derivation of

$$(C \Vdash C \quad v(\vec{n} \vec{T}) . (C \ n \ \text{let } x \ T = e \ \text{in } t$$

the interesting cases when

$$\begin{aligned} C \quad n \ \text{let } x \ T = \text{block in } t \\ C \quad n \ \text{let } x \ T = \text{return}(v \ T \ \text{in } t \end{aligned}$$

and

$$n \ t \ v/x \Vdash n \ \text{let } x \ T = \text{block in } t \quad v(\vec{n} \vec{T}) . (C \ n \ \text{let } x \ T = e \ \text{in } t$$

so by the induction hypothesis and by induction we have

$$\begin{aligned} (\Delta, \Phi \vdash C \ \Theta, \Sigma \xrightarrow{n \ \text{return } v} (\Delta, \Phi \ n \ t \ v/x \ \Theta, \Sigma \\ (\Delta, \Phi \ n \ t \ v/x \ \Theta, \Sigma \stackrel{s}{=} (\Delta, \Phi \ v(\vec{n} \vec{T}) . (C \ n \ \text{let } x \ T = e \ \text{in } t \ \Theta, \Sigma \end{aligned}$$

and

$$\begin{aligned} (\Delta, \Phi \vdash C \ \Theta, \Sigma \xrightarrow{n \ \text{return } v} (\Theta, \Phi \ n \ \text{let } x \ T = \text{block in } t \ \Delta, \Sigma \\ (\Theta, \Phi \ n \ \text{let } x \ T = \text{block in } t \ \Delta, \Sigma \stackrel{s}{=} (\Theta, \Phi \vdash C \ \Delta, \Sigma \end{aligned}$$

where

$$v(\Delta, \Theta, \Sigma \ \Delta, \Theta, \Sigma \ . v(\vec{n} \vec{T}) . (C \ n \ t \ \Vdash C \ v(\vec{n} \vec{T}) . (C \ n \ t$$

or symmetrically as required. □

Lemma A. If $C \Vdash C \quad C$ and $C \dashv^{\beta} 1$

and so we use the axiom to get

$$(\Delta, \Phi \vdash C \vdash \Theta, \Sigma \stackrel{s}{=} (\Delta, \Phi \vdash C \vdash \Theta, \Sigma$$

where we define

$$C \vdash (\vec{n} \vdash \vec{T}, \vec{n} \vdash \vec{T}) \text{ . } (C \vdash E \vdash n \text{ let } \vec{x} \vdash \vec{T} = \vec{e} \text{ in } t$$

- Case $(p \text{ dom}(C), n \text{ dom}(C))$
 we must have that

$$C = \nu(\vec{p}, \vec{U}). (C \text{ } p \text{ } O \text{ } n \text{ let } y \text{ } U = \text{block in } t$$

Moreover since C is write close we must have that the axioms

$$p \text{ } O \text{ } n \text{ let } x \text{ } T = p.l(\vec{v} \text{ in } t) \quad p \text{ } O \text{ } n \text{ let } x \text{ } T = O.l(p(\vec{v} \text{ in } t$$

in which case

$$(\Delta, \Phi \text{ } C \text{ } \Theta, \Sigma \xrightarrow{s \nu(\vec{n}, \vec{T}) . n \text{ call } p.l(\vec{v}} (\Delta, \Phi \text{ } C \text{ } \Theta, \vec{n}, \vec{T}, \Sigma$$

where we can

$$C = \nu(\vec{n}, \vec{T}). (C \text{ } n \text{ let } x \text{ } T = \text{block in } t$$

and we partition $\{\vec{n}, \vec{T}\}$ into $\{\vec{n}, \vec{T}\}, \{\vec{n}, \vec{T}\}$ such that $\{\vec{n}\} \cap \text{fn}(p.l(\vec{v} \text{ in } \{\vec{n}\})$
 $\cap \text{fn}(p.l(\vec{v} \text{ in } \{\vec{n}\}) = \emptyset$

we also have

$$(\Delta, \Phi \text{ } C \text{ } \Theta, \Sigma \xrightarrow{s \nu(\vec{n}, \vec{T}) . n \text{ call } p.l($$

B. Technical preliminaries

In a component $v(\Delta, (p, O, C)$

A component for $\Delta \quad r \text{---} s \text{---} \text{trace } \Theta$ resp $\dot{\Delta} \quad q \quad r \text{---} s \text{---} \text{trace } \Theta$ is one of the following

$v(\Theta(s \setminus \Theta(q) \cdot v(\text{ref} \text{---} \text{Ref} \cdot v(\text{state}_r \text{---} \text{State} \mid \Delta \quad r \text{---} r \text{---} \text{trace } \Theta) \cdot ($
 $\text{ref val} = \text{state}_r$
 $\prod\{\text{state}_r \text{---} \text{State}(\Delta \quad r \text{---} s \text{---} \text{trace } \Theta \mid \Delta \quad r \text{---} r \text{---} \text{trace } \Theta)\}$
 $\prod\{p \text{---} l_i = \text{ref.val.inCall}_{p,l_i} L_i \mid i = \dots n \mid p \text{---} l_i \text{---} L_i \mid i = \dots n \quad \Theta, \Theta(s)\}$
 $\prod\{n \text{---} t_n \text{---} \text{thread} \quad \Theta, \Theta(s)\}$
 $\prod\{n \text{---} t_n \text{---} \text{thread} \quad \Delta, \Delta(s \text{---} \text{an } n \text{---} \text{threads}(q))\}$

where t_n is a thread at n resp $\dot{\Delta} \quad r \text{---} s \text{---} \text{trace } \Theta$ resp $\dot{\Delta} \quad q \quad r \text{---} s \text{---} \text{trace } \Theta$

A thread at n for $\Delta \quad r \text{---} s \text{---} \text{trace } \Theta$ is one of the following

$\mid \text{let } x \text{---} T = \text{ref.val.out}_T(\text{in } t$
 $\quad \text{where } n \text{---} \text{output enab } e \text{---} \text{an } \Delta \text{---} r \text{---} \text{trace } \Theta \text{ and } t \text{---} \text{a return}(x \text{---} T \text{---} \text{thread at } n$
 $\quad \text{resp } \Delta \quad r \text{---} s \text{---} \text{trace } \Theta$
 $\mid \text{let } x \text{---} T = \text{block in } t$
 $\quad \text{where } n \text{---} \text{input enab } e \text{---} \text{an } \Delta \text{---} r \text{---} \text{trace } \Theta \text{ and } t \text{---} \text{a return}(x \text{---} T \text{---} \text{thread at } n$
 $\quad \text{resp } \Delta \quad r \text{---} s \text{---} \text{trace } \Theta$

A return($v \text{---} T$ thread at n for $\Delta \quad r \text{---} s \text{---} \text{trace } \Theta$ is one of the following

$\mid v$
 $\quad \text{where } n \text{---} \text{ba ance } \text{---} \text{an } n$
 $\mid \text{ref.val.inReturn}_T(v, t$
 $\quad \text{where } r = r \text{---} \text{ar } \text{---} a = v(\Theta \text{---} n \text{---} \text{call } p.l(\vec{v} \text{---} n \text{---} \text{ba ance } \text{---} \text{an } r$
 $\quad \text{and } t \text{---} \text{a thread at } n \text{---} \text{resp } \Delta \quad r \text{---} s \text{---} \text{trace } \Theta$
 $\mid \text{let } y \text{---} U = \text{return}(v \text{---} T \text{---} \text{in } t$
 $\quad \text{where } r = r \text{---} \text{ar } \text{---} a = v(\Theta \text{---} n \text{---} \text{call } p.l(\vec{v} \text{---} ? \text{---} n \text{---} \text{ba ance } \text{---} \text{an } r$
 $\quad \text{and } t \text{---} \text{a return}(y \text{---} U \text{---} \text{thread at } n \text{---} \text{resp } \Delta \quad r \text{---} s \text{---} \text{trace } \Theta$

Furthermore, Definition of a component $\dot{\Delta} \quad r \text{---} s \text{---} \text{trace } \Theta$ and $\dot{\Delta} \quad q \quad r \text{---} s \text{---} \text{trace } \Theta$

A thread at n for $\Delta \quad q \quad r \xrightarrow{s} \text{trace } \Theta$ is one of the following

- | stop
- | a thread at n_i or $\Delta \quad r \xrightarrow{s} \text{trace } \Theta$
where $\text{proj } n(q) = \text{proj } n(r)$
- | let $x \quad T = p.l(\vec{v})$ in t
where $\text{proj } n(qa) = \text{proj } n(r \quad a = v(\Theta \quad .n \text{ call } p.l(\vec{v}) \quad \text{an } t \text{ as a return}(x \quad T$
thread at n_i or $\Delta \quad r \xrightarrow{s} \text{trace } \Theta$
- | let $x \quad T = \text{return}(v \quad U)$ in t
where $\text{proj } n(qa) = \text{proj } n(r \quad a = v(\Theta \quad .n \text{ return } v \quad \text{an } t \text{ as a return}(x \quad T$
thread at n_i or $\Delta \quad r \xrightarrow{s} \text{trace } \Theta$
- | let $y \quad U = \text{ref.val.inCall}_{p.l.L}(\vec{v})$ in let $x \quad T = \text{return}(y \quad U)$ in t
where $\text{proj } n(q) = \text{proj } n(ra \quad a = v(\Delta \quad .n \text{ call } p.l(\vec{v}) \quad ? \text{ an } t \text{ as a return}(x \quad T$
thread at n_i or $\Delta \quad r \xrightarrow{s} \text{trace } \Theta$
- | t
where $\text{proj } n(q) = \text{proj } n(ra \quad a = v(\Delta \quad .n \text{ return } v \quad ? \text{ an } t \text{ as a return}(v \quad T$
thread at n_i or $\Delta \quad r \xrightarrow{s} \text{trace } \Theta_i$ or so $e \in T$
- | $\text{ref.val} = \text{new State}(\Delta \quad ra \xrightarrow{s} \text{trace } \Theta \quad , t$
where $\text{proj } n(q) = \text{proj } n(ra \quad \text{an } t \text{ as a thread at } n_i \text{ or } \Delta \quad ra \xrightarrow{s} \text{trace } \Theta$
- | t
where $n \quad t \xrightarrow{\beta} n \quad t$ an t as a thread at n_i or $\Delta \quad q \quad r \xrightarrow{s} \text{trace } \Theta$

Figure 1. Definition of a thread at n_i or $\Delta \quad q \quad r \xrightarrow{s} \text{trace } \Theta$

Proof An inspection of the definition of $\text{Comp}(\Delta \text{---} s \text{---} \text{trace } \Theta)$ □

Lemma B. If $\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta$ and $\Delta \text{---} C \text{---} \Theta$ is a component for $\Delta \text{---} r \text{---} s \text{---} \text{trace } \Theta$ then $(\Delta \text{---} C \text{---} \Theta) \stackrel{a}{=} (\Delta \text{---} C \text{---} \Theta)$ where C is a component for $\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta$.

Proof By considering the definition of $\Delta \text{---} r \text{---} s \text{---} \text{trace } \Theta$ we see that the following cases are exhaustive

Case $a = v(\Theta) \text{---} n \text{---} \text{return } v$ and $C = v(\Theta) \text{---} C \text{---} \text{ref val} = \text{state}_r \text{---} n \text{---} \text{let } y \text{---} U = \text{ref.val.out}_U(\text{ in } \text{let } x \text{---} T = \text{return}(y \text{---} U \text{ in } t)$

$\stackrel{e}{\text{have}}$

$(\Delta \text{---} C \text{---} \Theta)$

$\stackrel{\tau}{-} (\Delta \text{---} v(\Theta) \text{---} C \text{---} \text{ref val} = \text{state}_r \text{---} n \text{---} \text{let } y \text{---} U = \text{state}_r \text{---} \text{out}_U(\text{ in } \text{let } x \text{---} T = \text{return}(y \text{---} U \text{ in } t) \text{---} \Theta)$

$\stackrel{\beta}{-} (\Delta \text{---} v(\Theta) \text{---} C \text{---} \text{ref val} = \text{state}_r \text{---} n \text{---} \text{ref.val} = \text{new State}(\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta, \text{let } y \text{---} U = v \text{ in } \text{let } x \text{---} T = \text{return}(y \text{---} U \text{ in } t) \text{---} \Theta)$

$\stackrel{\tau}{-} (\Delta \text{---} v(\Theta, \text{state}_{ra} \text{---} \text{State}) \text{---} C \text{---} \text{ref val} = \text{state}_{ra} \text{---} \text{state}_{ra} \text{---} \text{State}(\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta) \text{---} n \text{---} \text{let } y \text{---} U = v \text{ in } \text{let } x \text{---} T = \text{return}(y \text{---} U \text{ in } t) \text{---} \Theta)$

$\stackrel{\beta}{-} (\Delta \text{---} v(\Theta, \text{state}_{ra} \text{---} \text{State}) \text{---} C \text{---} \text{ref val} = \text{state}_{ra} \text{---} \text{state}_{ra} \text{---} \text{State}(\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta) \text{---} n \text{---} \text{let } x \text{---} T = \text{return}(v \text{---} U \text{ in } t) \text{---} \Theta)$

$\stackrel{a}{-} (\Delta \text{---} v(\text{state}_{ra} \text{---} \text{State}) \text{---} C \text{---} \text{ref val} = \text{state}_{ra} \text{---} \text{state}_{ra} \text{---} \text{State}(\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta) \text{---} n \text{---} \text{let } x \text{---} T = \text{block in } t \text{---} \Theta, \Theta)$

with C as a component of $\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta$ as required

Case $a = v(\Theta) \text{---} n \text{---} \text{call } p.l(\vec{v})$ and $C = v(\Theta) \text{---} C \text{---} \text{ref val} = \text{state}_r \text{---} n \text{---} \text{let } y \text{---} U = \text{ref.val.out}_U(\text{ in } t)$

$\stackrel{e}{\text{have}}$

$(\Delta \text{---} C \text{---} \Theta)$

$\stackrel{\tau}{-} (\Delta \text{---} v(\Theta) \text{---} C \text{---} \text{ref val} = \text{state}_r \text{---} n \text{---} \text{let } y \text{---} U = \text{state}_r \text{---} \text{out}_U(\text{ in } t) \text{---} \Theta)$

$\stackrel{\beta}{-} (\Delta \text{---} v(\Theta) \text{---} C \text{---} \text{ref val} = \text{state}_r \text{---} n \text{---} \text{ref.val} = \text{new State}(\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta, \text{let } x \text{---} T = p.l(\vec{v} \text{ in } \text{ref.val.inReturn}_T(x, \text{let } y \text{---} U = \text{ref.val.out}_U(\text{ in } t) \text{---} \Theta)$

$\stackrel{\tau}{-} (\Delta \text{---} v(\Theta, \text{state}_{ra} \text{---} \text{State}) \text{---} C \text{---} \text{ref val} = \text{state}_{ra} \text{---} \text{state}_{ra} \text{---} \text{State}(\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta) \text{---} n \text{---} \text{let } x \text{---} T = p.l(\vec{v} \text{ in } \text{ref.val.inReturn}_T(x, \text{let } y \text{---} U = \text{ref.val.out}_U(\text{ in } t) \text{---} \Theta)$

$\stackrel{a}{-} (\Delta \text{---} v(\text{state}_{ra} \text{---} \text{State}) \text{---} C \text{---} \text{ref val} = \text{state}_{ra} \text{---} \text{state}_{ra} \text{---} \text{State}(\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta) \text{---} n \text{---} \text{let } x \text{---} T = \text{block in } \text{ref.val.inReturn}_T(x, \text{let } y \text{---} U = \text{ref.val.out}_U(\text{ in } t) \text{---} \Theta, \Theta)$

with C as a component of $\Delta \text{---} ra \text{---} s \text{---} \text{trace } \Theta$ as required

Case $a = v(\Delta) \text{---} n \text{---} \text{return } v$ and $C = C \text{---} \text{ref val} = \text{state}_r \text{---} n \text{---} \text{let } x \text{---} T = \text{block in } \text{ref.val.inReturn}_T(x, t)$

$e \xrightarrow{\text{ave}}$

$(\Delta \xrightarrow{C} \Theta$

-^a $(\Delta, \Delta \quad C \text{ ref val} = \text{state}_r$
 $n \text{ let } x \text{ } T = v \text{ in ref.val.inReturn}_T(x, t \xrightarrow{\Theta}$

-^{\beta} $(\Delta, \Delta \quad C \text{ ref val} = \text{state}_r$
 $n \text{ ref.val.inReturn}_T(v, t \xrightarrow{\Theta}$

-^{\tau} $(\Delta, \Delta \quad C \text{ ref val} = \text{state}_r$
 $n \text{ state}_r.\text{inReturn}_T(v, t \xrightarrow{\Theta}$

-^{\beta} $(\Delta, \Delta \quad C \text{ ref val} = \text{state}_r$
 $n \text{ ref.val} = \text{new State}(\Delta \text{ } ra \text{ } s \text{ } \text{trace } \Theta, t \xrightarrow{\Theta}$

-^{\tau} $(\Delta, \Delta \quad C \text{ v}(\text{state}_{ra} \text{ } \text{State} \text{ } .\text{ref val} = \text{state}_{ra} \text{ } \text{state}_{ra} \text{ } \text{State}(\Delta \text{ } ra \text{ } s \text{ } \text{trace } \Theta$
 $n \text{ } t \xrightarrow{\Theta}$

with e as a component f or $\Delta \text{ } ra \text{ } s \text{ } \text{trace } \Theta$ as require !

! Case $a = v(\Delta \text{ } .n \text{ call } p.l(\vec{v} \text{ } ? \text{ an } C \text{ } C \text{ ref val} = \text{state}_r \text{ } n \text{ let } x \text{ } T = \text{block in } t$

$e \xrightarrow{\text{ave}}$

$(\Delta \xrightarrow{C} \Theta$

-^a $(\Delta, \Delta \quad C \text{ ref val} = \text{state}_r$
 $n \text{ let } y \text{ } U = p.l(\vec{v} \text{ in let } x \text{ } T = \text{return}(y \text{ } U \text{ in } t \xrightarrow{\Theta}$

-^{\beta} $(\Delta, \Delta \quad C \text{ ref val} = \text{state}_r$
 $n \text{ let } y \text{ } U = \text{ref.val.inCall}_{p.lL}(\vec{v} \text{ in let } x \text{ } T = \text{return}(y \text{ } U \text{ in } t \xrightarrow{\Theta}$

-^{\tau} $(\Delta, \Delta \quad C \text{ ref val} = \text{state}_r$
 $n \text{ let } y \text{ } U = \text{state}_r.\text{inCall}_{p.lL}(\vec{v} \text{ in let } x \text{ } T = \text{return}(y \text{ } U \text{ in } t \xrightarrow{\Theta}$

-^{\beta} $(\Delta, \Delta \quad C \text{ ref val} = \text{state}_r$
 $n \text{ ref.val} = \text{new State}(\Delta \text{ } ra \text{ } s \text{ } \text{trace } \Theta, \text{ let } y \text{ } U = \text{ref.val.out}$

for Δ q r s trace Θ in F_x ures an with the nten e can n that a co ponent of
 Δ q r s trace Θ as per or e the trace q an t s s relate to so e pre x o s ote
that as pre x or er n on traces s contain n

Case C $C \text{ ref.val} = \text{state}_r$ $n \text{ ref.val} = \text{new State}(\Delta \text{ ra} \text{---} s \text{ trace } \Theta, t$
 $\text{---} \tau \text{---} v(\text{state}_{ra}^T \text{ State } . C \text{ ref.val} = \text{state}_{ra} \text{ state}_{ra} \text{ State}(\Delta \text{ ra} \text{---} s \text{ trace } \Theta \text{---} n \text{ } t \text{---} C$
 where t is a trace at n_i or $\Delta \text{ ra} \text{---} s \text{ trace } \Theta$

By definition C is a component i or $\Delta \text{ q } \text{ ra} \text{---} s \text{ trace } \Theta$

Case C $C \text{ n let } x \text{---} T = \text{ref.val.out}_T(\text{ in } t \text{---} \tau \text{---} C \text{ n let } x \text{---} T = \text{state}_r.\text{out}_T(\text{ in } t \text{---} C$
 where $\text{proj } n(q) = \text{proj } n(r \text{---} n \text{---} s \text{ output enab } e \text{---} n \Delta \text{---} r \text{---} s \text{ trace } \Theta$ and t is a return $(x \text{---} T$
 trace at n_i or $\Delta \text{ r} \text{---} s \text{ trace } \Theta$

$\vdash_i \Delta \text{ ra} \text{---} s \text{ trace } \Theta$ and $a = v(\Theta) \text{---} n \text{ call } p.l(\vec{v}) \text{---} \text{then}$

$$C \text{---} \beta \quad C \text{ n ref.val} = \text{new State}(\Delta \text{ ra} \text{---} s \text{ trace } \Theta, \text{---} \\ \text{ref.val.inReturn}_U(p.l(\vec{v}), \text{let } x \text{---} T = \text{ref.val.out}_T(\text{ in } t$$

where C is a component i or $\Delta \text{ q } \text{ r} \text{---} s \text{ trace } \Theta$ as required

$\vdash_i \Delta \text{ ra} \text{---} s \text{ trace } \Theta$ and $a = v(\Theta) \text{---} n \text{ return } v \text{---} \text{then}$ we must have that $r = r \text{---} v(\Theta) \text{---} n \text{ call } p.l(\vec{v}) \text{---} r$ where n is basic in r

Case $(\Delta \quad C n \text{ let } x \quad T = \text{block in } t \quad \Theta \quad \frac{v(\Delta \quad .n \text{ call } p.l(\vec{v}) \quad ?}{\Delta, \Delta \quad C n \text{ let } y \quad U = p.l(\vec{v} \text{ in let } x \quad T = \text{return}(y \quad U \text{ in } t \quad \Theta)}$

where $\text{projn}(q) = \text{projn}(r \quad n \quad s \quad \text{input enab } e \quad \text{in } \Delta \quad r \quad \text{trace } \Theta)$ and t is a $\text{return}(x \quad T)$ trace at n_i or $\Delta \quad r \quad s \quad \text{trace } \Theta$

e have

$$C \cdot^\beta \quad C n \text{ let } y \quad U = \text{ref.val.inCall}_{p.l.L}(\vec{v} \text{ in let } x \quad T = \text{return}(y \quad U \text{ in } t$$

where C is a component i or $\Delta \quad q a \quad r \quad s \quad \text{trace } \Theta$ as required

Case $(\Delta \quad C n \text{ let } x \quad T = \text{block in } t \quad \Theta \quad \frac{v(\Delta \quad .n \text{ return } v \quad ?}{\Delta, \Delta \quad C n \text{ let } x \quad T = v \text{ in } t \quad \Theta)}$

where $\text{projn}(q) = \text{projn}(r \quad n \quad s \quad \text{input enab } e \quad \text{in } \Delta \quad r \quad \text{trace } \Theta)$ and t is a $\text{return}(x \quad T)$ trace at n_i or $\Delta \quad r \quad s \quad \text{trace } \Theta$

e have

$$C \cdot^\beta \quad C n \text{ let } v/x$$

where C is a component i or $\Delta \quad q a \quad r \quad s \quad \text{trace } \Theta$ as required

Case $(\Delta \quad v(\Theta \quad .C n \text{ let } x \quad T = p.l(\vec{v} \text{ in } t \quad \Theta \quad \frac{v(\Theta \quad .n \text{ call } p.l(\vec{v}) \quad ?}{\Delta \quad C n \text{ let } x \quad T = \text{block in } t \quad \Theta, \Theta)}$

where $\text{projn}(q a) = \text{projn}(r \quad \text{in } t \quad \text{is a } \text{return}(x \quad T)$ trace at n_i or $\Delta \quad r \quad s \quad \text{trace } \Theta$

e have C is a component i or $\Delta \quad q a \quad r \quad s \quad \text{trace } \Theta$ as required

Case $(\Delta \quad v(\Theta \quad .C n \text{ let } x \quad T = \text{return}(y \quad U \text{ in } t \quad \Theta \quad \frac{v(\Theta \quad .n \text{ return } v \quad ?}{\Delta \quad C n \text{ let } x \quad T = \text{block in } t \quad \Theta, \Theta)}$

where $\text{projn}(q a) = \text{projn}(r \quad \text{in } t \quad \text{is a } \text{return}(x \quad T)$ trace at n_i or $\Delta \quad r \quad s \quad \text{trace } \Theta$

e have C is a component i or $\Delta \quad q a \quad r \quad s \quad \text{trace } \Theta$ as required □

Let e on y as the base case a appropriate use of Corollary B1

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